# Best Approximation in Finite Dimensional Subspaces of $\mathscr{L}(W, V)$ 

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#### Abstract

We prove Kolmogorov's type characterization of best approximation for given $L \in \mathscr{L}(W, V)$ in finite dimensional subspace $\mathscr{V} \subset \mathscr{L}(W, V)$. This extends the results obtained by Malbrock for the case $W=V=c_{0}$ and $W=C(T), V=C(S)$. © 1995 Academic Press, Inc.


## 1. Introduction

Let $X$ be a normed space over a field $K(K=\mathbb{R}$ or $K=\mathbb{C})$ and let $S_{X}$. denote the unit sphere in $X^{*}$. For $x \in X$ put

$$
\begin{equation*}
E(x)=\left\{f \in \operatorname{ext} S_{X^{*}}: f(x)=\|x\|\right\} \tag{1.1}
\end{equation*}
$$

(ext $W$ denotes the set of all extremal points of a given set $W$ ), and let for $Y \subset X$

$$
\begin{equation*}
\mathscr{P}_{Y}(x)=\{y \in Y:\|x-y\|=\operatorname{dist}(x, Y)\} . \tag{1.2}
\end{equation*}
$$

If $Y$ is a linear subspace of $X$ then the following Kolmogorov type characterization holds true.

Theorem 1.1 (see [2]). Assume $X$ is a normed space, $Y \subset X$ is its linear subspace, and let $x \in X \backslash Y$. Then $y_{0} \in P_{Y}(x)$ if and only if for every $y \in Y$ there exists $f \in E\left(x-y_{0}\right)$ with $r e f(y) \leqslant 0$.

A similar result can be proved in the case of strong unicity. In order to present it, let us recall that an element $y \in Y$ is called a strongly unique best approximation (briefly, SUBA) for $x \in X$ if and only if there exists $r>0$ such that for every $y \in Y$,

$$
\begin{equation*}
\|x-y\| \geqslant\left\|x-y_{0}\right\|+r \cdot\left\|y-y_{0}\right\| . \tag{1.3}
\end{equation*}
$$

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In [11, Theorem 2.1, p. 855] the following was shown.
Theorem 1.2. Let $x \in X \backslash Y$ and let $Y$ be a linear subspace of $X$. Then $y_{0} \in Y$ is a SUBA for $x$ with a constant $r>0$ if and only if for every $y \in Y$ there exists $f \in E\left(x-y_{0}\right)$ with $\operatorname{ref}(y) \leqslant-r\|y\|$.

If $Y$ is a finite dimensional subspace of $X$, then by [10, Theorem 1.1, p. 170] and Theorem 1.2 we get

Theorem 1.3. Assume $X$ is a normed space and $Y \subset X$ is a finite-dimensional linear subspace, and let $x \in X \backslash Y$. Then $y \in P_{Y}(x)$ (resp., $y$ is a SUBA for $x$ in $Y$ ) if and only if $\left.0 \in \operatorname{conv} E(x-y)\right|_{Y}\left(\right.$ resp., $\left.0 \in \operatorname{intconv} E(x-y)\right|_{Y}$, where $\left.E(x-y)\right|_{y}=\left\{\left.f\right|_{Y}: f \in E(x-y)\right\}$ ). (The symbols conv $A$ and int $A$ denote respectively the smallest convex set containing $A$ and the interior of $A$ with respect to the norm topology.)

In this note we consider the case when $X=\mathscr{L}(W, V)$ (the space of all linear continuous operators from a normed space $W$ into a normed space $V$ equipped with the operator norm) and $\mathscr{V} \subset X$ is a finitedimensional subspace. We prove Kolmogorov's type characterization of best approximants (Theorem 2.1) which involves only elements from the sets $S_{W}$ and ext $S_{V^{*}}$. (Note that a similar characterization for the case of compact operators was shown in [5].) We also present a result concerning strong unicity. This extends the results obtained in [7] and [8] for the spaces $W=V=c_{0}$ and $W=C(S), V=C(T)$. Next we characterize finitedimensional Chebyshev subspaces in the space $\mathscr{K}\left(c_{0}\right)$ of all compact operators going from $c_{0}$ into $c_{0}$.

## 2. General Case

Now we formulate the main result of this section.

Theorem 2.1. Let $W$, $V$ be arbitrary normed linear spaces (we consider the real and complex case) and let $\mathscr{V} \subset \mathscr{L}(W, V)$ be an $n$-dimensional subspace. Assume $L \in \mathscr{L}(W, V) \backslash \mathscr{r}$ and $V_{0} \in \mathscr{V}$. Then $V_{0} \in P_{y}(L)$ if and only if for every $\varepsilon>0$ there exists $m \in N, \varphi_{1}, \ldots, \varphi_{m} \in \operatorname{ext} S_{V^{*}}$, and $w_{1}, \ldots, w_{m} \in S_{W}$ such that

$$
\begin{equation*}
0 \in \operatorname{conv}\left\{\varphi_{1} \otimes w_{1}\left|v, \ldots, \varphi_{m} \otimes w_{m}\right| v\right\} \tag{2.1}
\end{equation*}
$$

and

$$
\begin{equation*}
\left|\sum_{i=1}^{m} \lambda_{i}\left(\varphi_{i} \otimes w_{i}\right)\left(L-V_{0}\right)-\left\|L-V_{0}\right\|\right| \leqslant \varepsilon, \tag{2.2}
\end{equation*}
$$

where $\lambda_{i}>0, \sum_{i=1}^{m} \lambda_{i}=1$. (We set $\left.\left(\varphi_{i} \otimes w_{i}\right)(L)=\varphi_{i}\left(L w_{i}\right).\right)$

Proof. Fix $\varepsilon>0$ and let $\mathscr{L}=[L] \oplus \mathscr{V}$. Since $\mathscr{L}$ is finite dimensional, $S_{\mathscr{L}}$ is a compact set. Hence there exist $C_{1}, \ldots, C_{m} \in S_{\mathscr{L}}$ such that $S_{\mathscr{L}} \subset \bigcup_{i=1}^{m} B_{d}\left(C_{i}, \varepsilon / 3\right)$. (The symbol $B_{d}(x, r)$ denotes the closed ball with a centre $x$ and a radius $r$.) Select for each $i \in\{1, \ldots, m\}, \varphi_{i} \in \operatorname{ext} S_{V^{*}}$ and $w_{i} \in S_{W}$ with

$$
\begin{equation*}
\left|\left\|C_{i}\right\|-\varphi_{i}\left(C_{i} w_{i}\right)\right| \leqslant \varepsilon / 3 \tag{2.3}
\end{equation*}
$$

Denote $Z_{1}=\left\{\varphi_{i} \otimes w_{i}: i=1, \ldots, m\right\}$ and $T=\left\{\varphi \otimes w: \varphi \in \operatorname{ext} S_{V^{*}}, w \in S_{w}\right\}$. Note that $\left.T\right|_{\mathscr{L}}$ is a total set over $\mathscr{L}$. Hence we can choose $\left.Z_{2} \subset T\right|_{\mathscr{L}}$, $Z_{2}=\left\{\left.\left(\gamma_{1} \otimes u_{1}\right)\right|_{\mathscr{L}}, \ldots,\left.\left(\gamma_{n+1} \otimes u_{n+1}\right)\right|_{\mathscr{L}}\right\}$ which forms a basis of $\mathscr{L}^{*}$. Put

$$
\begin{equation*}
Z=Z_{1} \cup Z_{2} \tag{2.4}
\end{equation*}
$$

and let $\mathscr{M}=\Gamma Z=$ absolutely convex hull of $Z$. Since $\mathscr{M}$ is an absolutely convex absorbing set, we can define $\|\|$-the Minkowski functional of the set $\mathscr{M}$ which is a norm in $\mathscr{L}^{*}$. Hence we can equip the space $\left(\mathscr{L}^{*}\right)^{*}=\mathscr{L}$ with a norm $\|A\|_{\varepsilon}=\max _{\gamma \in Z}|\gamma(A)|$. It is easy to observe that $\|\gamma\|_{. /}=\sup _{\|A\|_{t} \leqslant 1}|\gamma(A)|$ and, consequently, $\left\|\|_{\mathscr{A}}\right.$ is the dual norm for $\| \|_{\varepsilon}$ in $\mathscr{L}^{*}$. Now we will show that for every $A \in \mathscr{L},\left|\|A\|-\|A\|_{\varepsilon}\right| \leqslant \varepsilon\|A\|$. Of course, we can assume $A \neq 0$. Then

$$
\begin{aligned}
\left|1-\|(A /\|A\|)\|_{\varepsilon}\right| & =\left|\left\|C_{i}\right\|-\|(A /\|A\|)\|_{\varepsilon}\right| \\
& \leqslant\left|\left\|C_{i}\right\|-\left\|C_{i}\right\|_{\varepsilon}\right|+\left|\left\|C_{i}\right\|_{\varepsilon}-\|(A /\|A\|)\|_{\varepsilon}\right|
\end{aligned}
$$

where $C_{i} \in S_{\mathscr{L}}$ is chosen so that $\left\|(A /\|A\|)-C_{i}\right\| \leqslant \varepsilon / 3$. Hence

$$
\begin{aligned}
\left|1-\|(A /\|A\|)\|_{\varepsilon}\right| & \leqslant\left\|C_{i}-(A /\|A\|)\right\|_{\varepsilon}+\left|\left\|C_{i}\right\|-\left\|C_{i}\right\|_{\varepsilon}\right| \\
& \leqslant\left\|C_{i}-(A /\|A\|)\right\|+\varepsilon / 3 \leqslant(2 / 3) \varepsilon
\end{aligned}
$$

since by (2.3)

$$
\left\|C_{i}\right\|_{\varepsilon} \leqslant\left\|C_{i}\right\| \leqslant \varphi_{i}\left(C_{i} w_{i}\right)+\varepsilon / 3 \leqslant\left\|C_{i}\right\|_{\varepsilon}+\varepsilon / 3
$$

(by (2.4), $\varphi_{i} \otimes w_{i} \in Z_{1} \subset Z$ ). Consequently,

$$
\left|\|(A /\|A\|)\|-\|(A /\|A\|)\|_{\varepsilon}\right| \leqslant 2 \varepsilon / 3
$$

and

$$
\left|\|A\|-\|A\|_{\varepsilon}\right|<\varepsilon\|A\| .
$$

Hence we get immediately

$$
(1-\varepsilon)\|A\| \leqslant\|A\|_{\varepsilon} \leqslant(1+\varepsilon)\|A\| .
$$

From this, it is easy to deduce that

$$
\left|\operatorname{dist}(L, v)-\operatorname{dist}_{\varepsilon}(L, \mathscr{V})\right| \leqslant \varepsilon\|L\| .
$$

(dist ${ }_{\varepsilon}$ denotes the distance of $L$ from $\mathscr{V}$ with respect to the $\left\|\|_{c}\right.$.) Now let $V_{0} \in \mathscr{P}_{\gamma}(L)$ (see 1.1) and let $V_{\varepsilon} \in \mathscr{P}_{y}^{\varepsilon}(L)$ (the set of best approximants with respect to the $\left\|\|_{\varepsilon}\right.$ ). By Theorem 1.3, $\left.0 \in \operatorname{conv} E_{\varepsilon}\left(L-V_{\varepsilon}\right)\right|_{\text {, }}$ (see 1.1). It is evident by the definition of $\left\|\|_{\varepsilon}\right.$ that $E_{\varepsilon}\left(L-V_{\varepsilon}\right) \subset \bigcup_{\alpha \in K,|\alpha|=1} \alpha Z$. Hence $E_{\varepsilon}\left(L-V_{\varepsilon}\right)=\left\{\left.\varphi_{1} \otimes w_{1}\right|_{\mathscr{L}^{\prime}}, \ldots,\left.\varphi_{l} \otimes w_{l}\right|_{\mathscr{L}^{\prime}}\right\}$, where $\varphi_{i} \in \operatorname{ext} S_{+}$. and $w_{i} \in S_{w}$ for $i=1, \ldots, l$. Note that

$$
\begin{aligned}
\varepsilon\|L\| & \geqslant\left|\operatorname{dist}(L, \mathscr{V})-\operatorname{dist}_{\varepsilon}(L, \mathscr{V})\right| \\
& =\left|\left\|L-V_{0}\right\|-\left\|L-V_{\varepsilon}\right\|_{\varepsilon}\right| \\
& =\left|\left\|L-V_{0}\right\|-\sum_{i=1}^{1} \lambda_{i}\left(\varphi_{i} \otimes w_{i}\right)\left(L-V_{\varepsilon}\right)\right| \\
& =\left|\left\|L-V_{0}\right\|-\sum_{i=1}^{1} \lambda_{i}\left(\varphi_{i} \otimes w_{i}\right)\left(L-V_{0}\right)\right|
\end{aligned}
$$

where $\lambda_{i}>0, \sum_{i=1}^{l} \lambda_{i}=1$, and $\left.\sum_{i=1}^{l} \lambda_{i}\left(\varphi_{i} \otimes w_{i}\right)\right|_{y}=0$. This proves the first part of the theorem (if $\|L\| \neq 1$ we can start from $\varepsilon /\|L\|$ ).
Now suppose, on the contrary, that $V_{0} \notin \mathscr{P}_{y}(L)$ and condition (2.2) holds. Put $\varepsilon=\left(\left\|L-V_{0}\right\|-\operatorname{dist}(L, \mathscr{Y})\right) / 2$ and let $V_{1} \in \mathscr{P}_{\gamma}(L)$. Then

$$
\varepsilon+\left\|L-V_{1}\right\|<\left\|L-V_{0}\right\| \leqslant\left|\sum_{i=1}^{1} \lambda_{i}\left(\varphi_{i} \otimes w_{i}\right)\left(L-V_{0}\right)\right|+\varepsilon
$$

which by (2.1) gives

$$
\left\|L-V_{1}\right\|<\left|\sum_{i=1}^{1} \lambda_{i}\left(\varphi_{i} \otimes w_{i}\right)\left(L-V_{1}\right)\right|
$$

a contradiction.
Remark 2.2. In Theorem 2.1 the set ext $S_{V^{*}}$ can be replaced by any norming set $C \subset S_{V^{*}}$ and $S_{W^{*}}$ by any norming set $D \subset S_{W^{* *}}$ (A set $F \subset S_{V^{*}}$ is called a norming set iff $\|v\|=\sup _{f \in F}|f(v)|$ for every $v \in V$.)

Applying Theorem 2.1 we may prove a necessary condition for $\mathscr{V}$ to be a non-Chebyshev subspace. The method of the proof is similar to that of [8].

Theorem 2.3. Assume $\mathscr{V} \subset \mathscr{L}(W, V)$ is a non-Chebyshev finite-dimensional subspace (we consider the real case). Then there exists $D \in \mathscr{Y},\|D\|=1$
such that for every $\varepsilon>0$ there exists $f_{1}, \ldots, f_{m} \in \operatorname{ext} S_{V *}$ and $w_{1}, \ldots, w_{m} \in W$, $\sum_{i=1}^{m}\left\|w_{i}\right\|=1$ such that
(a) $G=\left.\sum_{i=1}^{m}\left(f_{i} \otimes w_{i}\right)\right|_{y}=0$;
(b) if $F \in \mathscr{L}^{*}(W, V)$ and $\|G \pm F\| \leqslant 1$ then $|F(D)|<\varepsilon$.
(c) $\sum_{i=1}^{m}\left|\left(f_{i} \otimes w_{i}\right)(D)\right|<\varepsilon$.

Proof. Since $\mathscr{V}$ is a non-Chebyshev subspace, there exists $L \in \mathscr{L}(W, V)$ such that $0, \pm D \in \mathscr{P}_{x}(L),\|D\|=1$. This will be the required $D$. Now fix $\varepsilon>0$. Applying Theorem 2.1, we can find $f_{1}, \ldots, f_{m} \in \operatorname{ext} S_{V^{*}}, u_{1}, \ldots, u_{m} \in$ $S_{W}, \lambda_{1}, \ldots, \lambda_{m} \geqslant 0$, and $\sum_{i=1}^{m} \lambda_{i}=1$ such that:

$$
\begin{equation*}
\left.\sum_{i=1}^{m} \lambda_{i}\left(f_{i} \otimes u_{i}\right)\right|_{r}=0 \tag{2.5}
\end{equation*}
$$

and

$$
\begin{equation*}
\left|\sum_{i=1}^{m} \lambda_{i}\left(f_{i} \otimes u_{i}\right)(L)-\|L\|\right|<\varepsilon / 2 . \tag{2.6}
\end{equation*}
$$

Put for $i=1, \ldots, m, w_{i}=\lambda_{i} u_{i}$. Now we check that $f_{1}, \ldots, f_{m}$ and $w_{1}, \ldots, w_{m}$ satisfy (a), (b), (c). Note that condition (a) is guaranteed by (2.5). To prove (b), fix $F \in \mathscr{L}^{*}(W, V),\|F \pm G\| \leqslant 1$. Hence $(F \pm G)(L) \leqslant\|L\|$. Since $\left.G\right|_{r}=0, \quad G(L) \pm F(L-D) \leqslant\|L-D\|=\|L\|$. By (2.6), $|F(L)|<\varepsilon / 2$ and $|F(L-D)|<\varepsilon / 2$. Hence $|F(D)|<\varepsilon$.

To show (c), put

$$
\begin{align*}
P & =\left\{i:\left(f_{i} \otimes w_{i}\right)(D) \geqslant 0\right\}, \\
P_{1} & =\left\{i:\left(f_{i} \otimes w_{i}\right)(D)>0\right\},  \tag{2.7}\\
U & =\left\{i:\left(f_{i} \otimes w_{i}\right)(D)<0\right\} .
\end{align*}
$$

If $U$ ( $P_{1}$ resp.) is empty, then by (2.5) $P_{1}$ ( $U$ resp.) is empty and (c) holds true. So assume that $U$ and $P_{1}$ are nonempty. Hence, by (2.5),

$$
\sum_{i \in P}\left|\left(f_{i} \otimes w_{i}\right)(D)\right|=\sum_{i \in U}\left|\left(f_{i} \otimes w_{i}\right)(D)\right|
$$

Now suppose that (c) does not hold. Then

$$
\sum_{i \in P}\left|\left(f_{i} \otimes w_{i}\right)(D)\right| \geqslant \varepsilon / 2
$$

and

$$
\begin{equation*}
\sum_{i \in U}\left|\left(f_{i} \otimes w_{i}\right)(D)\right| \geqslant \varepsilon / 2 . \tag{2.8}
\end{equation*}
$$

Put $\gamma_{P}=\sum_{i \in P}\left\|w_{i}\right\|$ and $\gamma_{U}=\sum_{i \in U}\left\|w_{i}\right\|$. By (2.7), $\gamma_{P}>0, \gamma_{U}>0$, and $\gamma_{U^{\prime}}+\gamma_{P}=1$. Set

$$
S_{1}=\sum_{i \in P}\left(f_{i} \otimes w_{i}\right)(L), \quad S_{2}=\sum_{i \in U}\left(f_{i} \otimes w_{i}\right)(L) .
$$

By (2.6) $S_{1}+S_{2}>\|L\|-\varepsilon / 2$. Thus either $S_{1}>\gamma_{p}(\|L\|-\varepsilon / 2)$ or $S_{2}>$ $\gamma_{L^{\prime}}(\|L\|-\varepsilon / 2)$. Suppose that $S_{1}>\gamma_{p}(\|L\|-\varepsilon / 2)$. Then by (2.7) and (2.8)

$$
\sum_{i \in P}\left(f_{i} \otimes w_{i}\right)(L+D)>\gamma_{P}\|L\|=\gamma_{P}\|L+D\|,
$$

since $0<\gamma_{P}<1$. But for each $i \in P$,

$$
\begin{equation*}
\left(f_{i} \otimes w_{i}\right)(L+D) \leqslant\left\|w_{i}\right\|\|L+D\| . \tag{2.9}
\end{equation*}
$$

By summing both sides of (2.9) we get a contradiction.
If $S_{2}>\gamma_{U}(\|L\|-\varepsilon / 2)$ then a similar argument using $U$ and $L-D$ provides a contradiction. The proof of Theorem 2.3 is complete.

Now we consider the case of strong unicity.
Theorem 2.4. Let $X$ be a normed real space and let $V \subset X$ be an $n$-dimensional subspace with a basis $v_{1}, \ldots, v_{n}$. Let $S \subset S_{X}$. be a norming set. Assume furthermore that there is $\delta>0$ such that for every set $f_{1}, \ldots, f_{n}$ of linearly independent functionals from $S$

$$
\begin{equation*}
\left|\operatorname{det}\left[f_{i}\left(v_{j}\right)\right]_{i, j=1, \ldots, n}\right|>\delta>0 \tag{2.10}
\end{equation*}
$$

( $\operatorname{det} A$ denotes the determinant of a matrix A.) Then each $x \in X$ has $a$ strongly unique best approximation in $V$.

Proof. Fix $x \in X \backslash V$ and consider $Z=[x] \oplus V$. Since $Z$ as a finitely dimensional subspace is separable, we can assume that $S$ is countable. By the totality of $S$ over $Z$, we can choose $k_{0} \in N$ such that $\left\{\phi_{1}, \ldots, \phi_{k_{0}}\right\}$ is total over $Z$. Hence for each $k \geqslant k_{0}$ we can equip $Z$ with a norm

$$
\|z\|_{k}=\max _{i=1, \ldots k}\left|s_{i}(z)\right| \quad\left(S=\left\{s_{1}, s_{2}, \ldots\right\}\right)
$$

By (2.10) $V$ with $\left\|\|_{k}\right.$ is an interpolating subspace of $Z$. Hence for $k \geqslant k_{0}$ there exists $v_{k} \in V$ which is a SUBA (see 1.3 ) for $x$ with respect to the $\left\|\|_{k}\right.$. By Theorem 1.3, $0 \in$ int conv $\left.E_{k}\left(x-v_{k}\right)\right|_{v}$ (see 1.1 ). (We consider the set $E_{k}\left(x-v_{k}\right)$ with respect to the $\left\|\|_{k}\right.$.) By Carathéodory's theorem $0=\left.\sum_{i=1}^{n+1} \lambda_{i}^{k} f_{i}^{k}\right|_{v}$, where $f_{1}^{k}, \ldots, f_{n+1}^{k} \in E_{k}\left(x-v_{k}\right), \lambda_{i}^{k}>0$, and $\sum_{i=1}^{n+1} \lambda_{i}^{k}=1$. Passing to a subsequence if necessary, we can assume $v_{k} \rightarrow v_{0}, \lambda_{i}^{k} \rightarrow \lambda_{i}$, and $f_{i}^{k} \rightarrow f_{i} \in S_{Z^{*}}$.

It is evident that $f_{i}\left(x-v_{0}\right)=\left\|x-v_{0}\right\|$ and $\left.\sum_{i=1}^{n+1} \lambda_{i} f_{i}\right|_{V}=0$. Now we show that $\lambda_{i}>0$ for $i=1, \ldots, n+1$. Note that $\lambda_{i_{0}}>0$ for some $i_{0} \in\{1, \ldots, n+1\}$, since $\sum_{i=1}^{n+1} \lambda_{i}=1, \lambda_{i} \geqslant 0$ for $i=1, \ldots, n+1$. We can assume $i_{0}=n+1$. By the Cramer rule,

$$
\begin{equation*}
\lambda_{i}^{k}=\lambda_{n+1}^{k} \cdot \Delta_{i}^{k} / A_{n+1}^{k} \quad \text { for } \quad i=1, \ldots, n \tag{2.11}
\end{equation*}
$$

where

$$
\Delta_{i}^{k}=(-1)^{i+1} \operatorname{det}\left[f_{l}^{k}\left(v_{j}\right)\right]_{j=1, \ldots, n, l=1, \ldots, n+1, l \neq i}
$$

Hence, by (2.11), $1 /\left|\lambda_{i}^{k}\right| \leqslant M / \delta \cdot 2 /\left|\lambda_{n+1}\right|$ for $k$ sufficiently large and $M>0$ independent of $k$. Consequently, $\lambda_{i}=\lim _{k \rightarrow \infty} \lambda_{i}^{k}>0$. Now take $w \in V \backslash\{0\}$. Since the set $\left\{\left.f_{1}\right|_{V}, \ldots,\left.f_{n+1}\right|_{V}\right\}$ is total over $V, f_{i 0}(w)<0$ for some $i_{0} \in\{1, \ldots, n+1\}$. From this we derive that $f(w)<0$ for some $f \in \operatorname{ext}\left\{g \in S_{Z^{*}}: g\left(x-v_{0}\right)=\left\|x-v_{0}\right\|\right\}$. An easy calculation shows that $f \in E\left(x-v_{0}\right)$ (see 1.1). Note that a function $G: S_{V} \ni w \rightarrow \inf \{g(w)$ : $\left.g \in E\left(x-v_{0}\right)\right\}$ is upper semicontinuous and, by the above reasoning, $G(w)<0$ for every $w \in S_{V}$. By the compactness of $S_{V}$ we get $\sup \left\{G(w): w \in S_{V}\right\}=-r<0$. Now fix $v \in V \backslash\{0\}$ and take $f \in E\left(x-v_{0}\right)$ with $f(v /\|v\|)<G(v /\|v\|)+r / 2$. Hence $f(v /\|v\|)<-r / 2$ and consequently $f(v)<-r / 2 \cdot\|v\|$.

By Theorem 1.2, $v_{0}$ is a SUBA for $x$ in $V$, which completes the proof of the theorem.

Remark 2.5. By ([7, Theorem 3.3]) the term $\delta$ in (2.10) is essential. Here

$$
S=\left\{e_{i} \otimes x: x \in \operatorname{ext} S_{l^{x}}, e_{i} \in \operatorname{ext} S_{l_{1}}\right\}
$$

Example 2.6. Assume $W=V=c_{0}$. Let $A \in \mathscr{L}(W, V)$ be so chosen that for every $i \in N, x \in \operatorname{ext} S_{I^{\infty}}$,

$$
\left|(A x)_{i}\right|>\delta>0
$$

Then, by Theorem 2.4, each $L \in \mathscr{L}(W, V)$ has a strongly unique best approximation in [A]. (The set $S$ is the same as in Remark 2.5.)

Example 2.7. Assume $W=l_{1}, V=c_{0}$. Let $A \in \mathscr{L}(W, V)$ be represented as an infinite matrix $[A(i, j)]_{i, j=1,2, \ldots}$. If there exists $\delta>0$ such that for every $i, j \in N|A(i, j)|>\delta>0$, then each $L \in \mathscr{L}(W, V)$ possesses a strongly unique best approximation in [ $A$ ]. Here

$$
S=\left\{e_{i} \otimes e_{j}: i, j=1,2, \ldots, e_{i}, e_{j} \in \operatorname{ext} S_{l}\right\}
$$

## 3. Strong Unicity in $\mathscr{K}\left(c_{0}\right)$

We start with the following

Theorem 3.1. Let $\mathscr{V} \subset \mathscr{K}\left(c_{0}\right)$ be a finite dimensional Chebyshev subspace. (The symbol $\mathscr{K}\left(c_{0}\right)$ denotes the space of all compact operators from $c_{0}$ into $c_{0}$; we consider the real case $)$. Then each $L \in \mathscr{K}\left(c_{0}\right)$ has a strongly unique best approximation in $\mathscr{V}$.

Proof. Assume that there exists $L_{0} \in \mathscr{K}\left(c_{0}\right) \backslash \mathscr{V}$ such that $V_{0} \in \mathscr{P}_{y}\left(L_{0}\right)$ (see (1.2)) is not a SUBA for $L_{0}$ in $\mathscr{V}$. Put

$$
\begin{equation*}
I=\left\{i \in N:\left\|e_{i} \circ\left(L_{0}-V_{0}\right)\right\|=\left\|L_{0}-V_{0}\right\|\right\} . \tag{3.1}
\end{equation*}
$$

(We denote $e_{i}(x)=x_{i}$ for $x \in c_{0}$.) By [9],

$$
\begin{equation*}
\operatorname{ext} S_{\mathscr{K}\left(c_{0}\right)}=\operatorname{ext} S_{l^{\prime}} \otimes \operatorname{ext} S_{l^{x}} \tag{3.2}
\end{equation*}
$$

Hence

$$
\left\|L_{0}-V_{0}\right\|=\left(e_{i} \otimes x^{i}\right)\left(L_{0}-V_{0}\right)
$$

for all $e_{i} \otimes x^{i} \in E\left(L_{0}-V_{0}\right)$ (see 1.1). Consequently, the set $I$ is nonempty. For each $i \in I$ define

$$
\begin{equation*}
Z_{i}=\left\{x \in \operatorname{ext} S_{l^{x}}:\left(e_{i} \otimes x\right)\left(L_{0}-V_{0}\right)=\left\|L_{0}-V_{0}\right\|\right\} . \tag{3.3}
\end{equation*}
$$

Since $V_{0} \in \mathscr{P}_{1}\left(L_{0}\right)$, by Theorem 1.1, for every $V \in \mathscr{V}$ there exists $i \in I$ and $x^{i} \in Z_{i}$ such that

$$
\begin{equation*}
\left(e_{i} \otimes x^{i}\right)(V) \leqslant 0 \tag{3.4}
\end{equation*}
$$

Since $V_{0}$ is not a SUBA for $L_{0}$ and $\mathscr{V}$ is finite dimensional, by Theorem 1.2, there exists $V_{1} \in S_{y}$. such that for every $i \in I$ and $x \in Z_{i}$

$$
\begin{equation*}
\left(e_{i} \otimes x\right)\left(V_{1}\right) \geqslant 0 . \tag{3.5}
\end{equation*}
$$

Now assume that we have constructed $L \in \mathscr{K}\left(c_{0}\right)$ such that

$$
\begin{equation*}
\left\|L-\alpha V_{\mathbf{1}}\right\| \leqslant\|L\| \tag{3.6}
\end{equation*}
$$

for $\alpha \in\left[0, x_{0}\right)$ and

$$
\begin{equation*}
\left(e_{i} \otimes x\right)(L)=\|L\| \tag{3.7}
\end{equation*}
$$

for every $i \in I$ and $x \in Z_{i}$. By Theorem 1.1, (3.4), and (3.6), $\alpha V_{1} \in \mathscr{P}_{P}(L)$ for every $\alpha \in\left[0, \alpha_{0}\right)$, which contradicts the fact that $\mathscr{V}$ is a Chebyshev subspace. So to finish the proof, it is necessary to construct an $L \in \mathscr{K}\left(c_{0}\right)$
satisfying (3.6) and (3.7). To do this, fix $i \in I$ and $x=\left(x_{1}, x_{2}, \ldots\right) \in Z_{i}$. If $\sum_{k=1}^{\infty}\left|V_{1}(i, k)\right|=0\left(V_{1}\right.$ is represented by a matrix $\left.\left[V_{1}(i, k)\right]_{i, k=1,2, \ldots}\right)$ then define

$$
\begin{equation*}
L_{i}=(L(i, k))_{k=1,2} \ldots, \tag{3.8}
\end{equation*}
$$

where

$$
L(i, k)=L_{0}(i, k)-V_{0}(i, k)
$$

(Here $\left[L_{0}(i, k)\right]_{i, k=1,2, \ldots}$ denote the matrix corresponding to $L_{0}$ and $\left[V_{0}(i, k)\right]_{i, k=1,2, \ldots}$ the matrix corresponding to $V_{0}$ ).

If $\sum_{k=1}^{\infty}\left|V_{1}(i, k)\right|>0$, then put

$$
\begin{equation*}
U_{i}=\left\{k \in N: L_{0}(i, k)-V_{0}(i, k)=0\right\} \tag{3.9}
\end{equation*}
$$

Since $\left\|e_{i} \circ\left(L_{0}-V_{0}\right)\right\|=\operatorname{dist}\left(L_{0}, \mathscr{V}\right)>0, U_{i} \neq N$. Put

$$
\begin{align*}
& F_{i}=\left\{k \in N \backslash U_{i}: x_{k}=\operatorname{sgn} V_{1}(i, k)\right\},  \tag{3.10}\\
& E_{i}=N \backslash\left(U_{i} \cup F_{i}\right) . \tag{3.11}
\end{align*}
$$

Take $y=\left(y_{1}, y_{2}, \ldots,\right) \in \operatorname{ext} S_{l^{x}}$ given by

$$
y_{k}=\left\{\begin{array}{lll}
x_{k} & \text { for } & k \in F_{i} \cup E_{i}  \tag{3.12}\\
-\operatorname{sgn} V_{1}(i, k) & \text { for } & k \in U_{i} .
\end{array}\right.
$$

By (3.9) and (3.12), $\left(e_{i} \otimes y\right)\left(L_{0}-V_{0}\right)=\left\|L_{0}-V_{0}\right\|$. According to (3.5),

$$
\begin{equation*}
\left(e_{i} \otimes y\right)\left(V_{1}\right)=\sum_{k \in F_{i}}\left|V_{1}(i, k)\right|-\sum_{k \in\left(U_{i} \cup E_{i}\right)}\left|V_{1}(i, k)\right| \geqslant 0 . \tag{3.13}
\end{equation*}
$$

From this we derive $F_{i} \neq \varnothing$, since $\sum_{k=1}^{\infty}\left|V_{1}(i, k)\right|>0$. Define for $k \in N$,

$$
L(i, k)=\left\{\begin{array}{lll}
V_{1}(i, k) & \text { for } & k \in F_{i}  \tag{3.14}\\
0 & \text { for } & k \in N \backslash F_{i}
\end{array}\right.
$$

and set $L_{i}=(L(i, 1), L(i, 2), \ldots)$. We show that for $\alpha \in[0,1), \beta \geqslant 1$,

$$
\begin{equation*}
\sum_{k=1}^{\infty}\left|\beta L(i, k)-\alpha V_{1}(i, k)\right| \leqslant \beta \cdot \sum_{k=1}^{\infty}|L(i, k)| . \tag{3.15}
\end{equation*}
$$

To do this, take any $z \in \operatorname{ext} S_{l \infty}$. If $z_{k}=x_{k}$ for every $k \in F_{i}$ then

$$
\left(e_{i} \otimes z\right)\left(V_{1}\right)=\sum_{k=1}^{\infty} V_{1}(i, k) z_{k}=\sum_{k \in F_{i}}\left|V_{1}(i, k)\right|+\sum_{k \in E_{i} \cup U_{i}} V_{1}(i, k) z_{k} \geqslant 0
$$

by (3.13). Hence

$$
\begin{aligned}
\sum_{k=1}^{\infty}\left(\beta L(i, k)-\alpha V_{1}(i, k)\right) z_{k} & =\sum_{k=1}^{\infty} \beta L(i, k) z_{k}-\alpha \cdot \sum_{k=1}^{\infty} V_{1}(i, k) z_{k} \\
& =\beta \cdot \sum_{k \in F_{i}}|L(i, k)|-\alpha \cdot \sum_{k=1}^{\infty} V_{1}(i, k) z_{k} \\
& \leqslant \beta \cdot \sum_{k=1}^{\infty}|L(i, k)| .
\end{aligned}
$$

If $z_{k}=-x_{k}$ for some $k \in F_{i}$, then the set $F_{i}^{1}=\left\{k \in F_{i}: x_{k}=-z_{k}\right\}$ is nonempty. Compute

$$
\begin{aligned}
& \sum_{k=1}^{\infty}\left(\beta L(i, k)-\alpha V_{1}(i, k)\right) z_{k} \\
& =\sum_{k \in F_{i}^{\prime}}\left(\beta L(i, k)-\alpha V_{1}(i, k)\right) z_{k}+\sum_{k \in\left(F_{i} \backslash F_{i}^{\prime}\right) \cup E_{i} \cup U_{i}}\left(\beta L(i, k)-\alpha V_{1}(i, k)\right) z_{k} \\
& =\sum_{k \in F_{i}^{\prime}}(\alpha-\beta)\left|V_{1}(i, k)\right|+\sum_{\left.k \in F_{i} \backslash F_{i}^{\prime}\right) \cup E_{i} \cup U_{i}}\left(\beta L(i, k)-\alpha V_{1}(i, k)\right) z_{k} \\
& \leqslant \sum_{k \in F_{i}^{\prime}}(\beta-\alpha)\left|V_{1}(i, k)\right|+\sum_{k \in F_{i} \not F_{l}^{\prime}}(\beta-\alpha)\left|V_{1}(i, k)\right|+\sum_{k \in E_{i} \cup U_{1}}-\alpha V_{1}(i, k) z_{k} \\
& =\sum_{k \in F_{i}} \beta\left|V_{1}(i, k)\right|-\alpha \cdot\left(\sum_{k \in F_{i}}\left|V_{1}(i, k)\right|+\sum_{k \in E_{i} \cup U_{i}} V_{1}(i, k) z_{k}\right) \\
& \leqslant \beta \cdot \sum_{k \in F_{i}} \mid\left(V_{1}(i, k) \mid\right. \\
& =\beta \cdot \sum_{k=1}^{\infty}|L(i, k)|
\end{aligned}
$$

(see 3.13).
Now if $i \notin I$ then we define $L_{i}=(L(i, 1), L(i, 2) \ldots$,$) by$

$$
\begin{equation*}
L(i, k)=L_{0}(i, k)-V_{0}(i, k) \quad \text { for } \quad k=1,2, \ldots \tag{3.16}
\end{equation*}
$$

Finally observe that by the Schur theorem (see [4, p. 864]) for $i \geqslant i_{0}$

$$
\left\|e_{i} \circ\left(L_{0}-V_{0}\right)\right\| \leqslant \operatorname{dist}\left(L_{0}, \mathscr{V}\right) / 2
$$

Hence the set $I$ is finite and

$$
\begin{equation*}
M=\sup _{i \in N \backslash \backslash}\left\|e_{i} \circ\left(L_{0}-V_{0}\right)\right\|<\left\|L_{0}-V_{0}\right\| . \tag{3.17}
\end{equation*}
$$

Following (3.15) for $i \in I$ we can modify, if necessary, the rows $L_{i}$ defined by (3.8) and (3.14), multiplying them by constants $\beta_{i} \geqslant 1$ such that

$$
\left\|L_{i}-\alpha V_{1}(i, \cdot)\right\|_{1}<\left\|L_{i}\right\|_{1}=a>\left\|L_{0}-V_{0}\right\|
$$

for $\alpha \in[0,1)$. Now choose $\alpha_{0} \in(0,1)$ such that $M+\alpha_{0}<\left\|L_{0}-V_{0}\right\|$. By (3.17), for $\alpha \in\left[0, \alpha_{0}\right)$ and $i \in N \backslash I$,

$$
\left\|L_{i}-\alpha V_{1}(i,)\right\|_{1}<\left\|L_{0}-V_{0}\right\| .
$$

Hence, by following (3.8), (3.14), and (3.15), the operator $L$ defined by (3.8), (3.14), and (3.16) satisfies (3.6) for $\alpha \in\left[0, \alpha_{0}\right.$ ) and (3.7) for all $i \in I$ and $x \in Z_{i}$. The proof of Theorem 3.1 is complete.

Note that the unicity of best approximation for given $L \in \mathscr{K}\left(c_{0}\right)$ in $\mathscr{V}$ does not force the strong unicity because of

Example 3.2. Let $\dot{L}=[L(i, k)]_{i, k=1,2, \ldots}$ and $V=[V(i, k)]_{i, k=1,2, \ldots}$ be defined by

$$
\begin{aligned}
& L(i, k)=\left\{\begin{array}{lll}
0 & \text { if } i \neq 1 \\
1 / k^{3} & \text { if } i=1
\end{array}\right. \\
& V(i, k)=\left\{\begin{array}{lll}
0 & \text { if } i \neq 1 \\
(-1)^{k} / k^{2} & \text { for } i=1, & k>1 \\
-\sum_{l=2}^{\infty}(-1)^{t} / l^{2} & \text { for } i=1, & k=1
\end{array}\right.
\end{aligned}
$$

Let $\mathscr{V}=[V]$. We show that 0 is the unique best approximation for $L$ in $\mathscr{V}$. Take $\alpha \in R \backslash\{0\}$. If $\alpha>0$, choose an even number $k_{0}$ such that $\alpha / k_{0}^{2}>1 / k_{0}^{3}$. Let $z=\left(z_{1}, z_{2}, \ldots\right) \in \operatorname{ext} S_{1} \times$ be given by

$$
z_{k}=\left\{\begin{array}{lll}
1 & \text { if } & k \neq k_{0} \\
-1 & \text { if } & k=k_{0}
\end{array}\right.
$$

Then

$$
\begin{aligned}
\|L-\alpha V\| & \geqslant\left(e_{1} \otimes z\right)(L-V) \\
& =\sum_{l=1}^{\infty} z_{l}(L(1, l)-\alpha V(1, l)) \\
& =\sum_{l=1}^{\infty}(L(1, l)-V(1, l))+2\left(\alpha / k_{0}^{2}-1 / k_{0}^{3}\right) \\
& >\sum_{l=1}^{\infty} L(1, l)=\|L-0\|
\end{aligned}
$$

since $\sum_{i=1}^{\infty} V(1, l)=0$. If $\alpha<0$, choose $k_{0}$ odd such that $-\alpha / k_{0}^{2}>1 / k_{0}^{3}$.
Reasoning as above we get $\|L-\alpha V\|>\|L\|$. Hence $0 \in \mathscr{P},(L)$ is the unique best approximation. However, $E(L-0)=\left\{e_{1} \otimes(1,1, \ldots)\right\}$ (see (3.2) and $(1.1))$. Since $e_{1} \otimes(1,1, \ldots)(V)=0$, by Theorem 1.20 is not a SUBA for $L$ in $r$.

Remark 3.3. If we replace $c_{0}$ by $l_{\infty}^{m}$, then by [3, Theorem 2.2(a)] or [9] the set ext $S_{\mathscr{*} \cdot\left(l_{x}^{m}\right)}$ is finite. By [6], if $\mathscr{r}$ is a subspace of $\mathscr{K}\left(l_{x}^{m}\right)$ then $L \in \mathscr{K}\left(l_{r_{x}}^{m}\right)$ has a unique best approximation in $\mathscr{V}$ if and only if $L$ has a strongly unique best approximation in $\mathscr{V}$.

Corollary 3.4. If $V \in S_{\mathscr{X ( c _ { 0 } )}}$ then $\mathscr{V}=[V]$ is a Chebyshev subspace if and only if for every $i \in N$ and $x \in \operatorname{ext} S_{l^{x}}$,

$$
\begin{equation*}
\left(e_{i} \otimes x\right)(V) \neq 0 \tag{3.18}
\end{equation*}
$$

## Comparing Corollary 3.4 with Theorem 3.3 of [7] we get

Proposition 3.5. There exists

$$
\varphi \in \operatorname{ext} S_{\mathscr{L}^{*}((0))} \backslash\left\{e_{i} \otimes x: i=1,2, \ldots, x \in \operatorname{ext} S_{i \times}\right\}
$$

Proof. If ext $S_{\mathscr{P}^{*}}\left(c_{0}\right) \subset\left\{\left(e_{i} \otimes x\right): i=1,2, \ldots, x \in \operatorname{ext} S_{1 \times}\right\}$ then by Theorems 1.1 and 1.2 each $V$ satisfying (3.18) defines a Chebyshev subspace in $\mathscr{L}\left(c_{0}\right)$ which contradicts Theorem 3.3 of [7].

Proposition 3.5 shows that Theorem 2.2(a) of [3] cannot be generalized from the case compact operators to the case of linear operators.

At the end of this section we present an example of a two-dimensional Chebyshev subspace in $\mathscr{K}\left(c_{0}\right)$. The reasoning presented here is similar to that of [1]. First we recall, after [1],

Lemma 3.6. Let $M>1$ be given. Assume $f(r)=\sum_{n=0}^{\infty} a_{n} r^{n}$ is a power series whose coefficients are not all 0 . Assume that if $a_{n} \neq 0$ then

$$
1 \leqslant\left|a_{n}\right| \leqslant M .
$$

Then for every $r \in(0,1 /(M+1)), f(r) \neq 0$.

Proof. Let $N$ denote the smallest index $n$ such that $a_{n} \neq 0$. Then

$$
\begin{aligned}
|f(r)| & =\left|\sum_{n=N}^{\infty} a_{n} r^{n}\right| \geqslant\left|a_{N} \cdot r^{N}\right|-\sum_{n=N+1}^{\infty}\left|a_{n}\right||r|^{n} \\
& \geqslant|r|^{N}-M|r|^{N+1} /(1-|r|) \\
& =|r|^{N} /(1-|r|)(1-|r|(1+M))>0 .
\end{aligned}
$$

Example 3.7. Let $c \in(0,1), r \in(0,1 / 4)$. Define

$$
\begin{array}{ll}
V_{1}(i, k)=c^{i} \cdot r^{2^{2 k+1}} & \text { for } i, k=1,2, \ldots \\
V_{2}(i, k)=(c / 2)^{i} \cdot r^{2^{2 k+2}} & \text { for } i, k=1,2, \ldots \tag{3.20}
\end{array}
$$

We show that $V_{1}, V_{2}$ defined by (3.19) and (3.20) form a two-dimensional interpolating (hence Chebyshev) subspace in $\mathscr{K}\left(c_{0}\right)$. To do this, take $\varphi_{1}=e_{i_{1}} \otimes x_{1}, \varphi_{2}=e_{i_{2}} \otimes x_{2}$ to be two linearly independent functionals from ext $S_{\mathscr{K}^{*}\left(c_{0}\right)}$. We prove that $\operatorname{det}\left[\varphi_{i}\left(V_{j}\right)\right]_{i, j=1,2} \neq 0$. Let $x_{j}=\left(\sigma_{1 j}, \sigma_{2 j}, \ldots\right)$ for $j=1,2\left(\sigma_{i j}= \pm 1\right)$. Note that

$$
\begin{aligned}
& \operatorname{det}\left[\varphi_{i}\left(V_{j}\right)\right]_{i, j=1,2}=\operatorname{det}\left[\begin{array}{l}
\sum_{j=1}^{\infty} \sigma_{1 j} V_{1}\left(i_{1}, j\right), \sum_{j=1}^{\infty} \sigma_{1 j} V_{2}\left(i_{1}, j\right) \\
\sum_{j=1}^{\infty} \sigma_{2 j} V_{1}\left(i_{2}, j\right), \sum_{j=1}^{\infty} \sigma_{2 j} V_{2}\left(i_{2}, j\right)
\end{array}\right] \\
& =\sum_{j_{1}, j_{2}=1}^{\infty} \operatorname{det}\left[\begin{array}{l}
\sigma_{1 j_{1}} V_{1}\left(i_{1}, j_{1}\right), \sigma_{1 j_{2}} V_{2}\left(i_{1}, j_{2}\right) \\
\sigma_{2 j_{1}} V_{1}\left(i_{2}, j_{1}\right), \sigma_{2 j_{2}} V_{2}\left(i_{2}, j_{2}\right)
\end{array}\right] \\
& =\sum_{j_{1}, j_{2}=1}^{\infty} \operatorname{det}\left[\begin{array}{l}
\sigma_{1 j_{1}} c^{i_{1}} 2^{2^{2 / 1}+1}, \sigma_{1 j_{2}}(c / 2)^{i_{1}} r^{2^{2 / 2}+2} \\
\sigma_{2 j_{1}} c^{i^{2}} r^{2^{2 i_{1}}+1}, \sigma_{2 j_{2}}(c / 2)^{i_{2}} r^{2^{2 j_{2}+2}}
\end{array}\right] \\
& =\sum_{j, j 2=1}^{\infty} r^{2^{2 j_{1}+1}+2^{2 j_{2}+2}} \cdot \operatorname{det}\left[\begin{array}{l}
\sigma_{1 j_{1}} c^{i_{1}}, \sigma_{1 j_{2}}(c / 2)^{i_{1}} \\
\sigma_{2 j_{1}} c^{i_{2}}, \sigma_{2 j_{2}}(c / 2)^{i_{2}}
\end{array}\right] .
\end{aligned}
$$

If $2^{2 j_{1}+1}+2^{2 j_{2}+2}=2^{2 k_{1}+1}+2^{2 k_{2}+2}$, because of the unique binary expression of each integer we get $j_{1}=k_{1}$ and $j_{2}=k_{2}$. In particular, then, distinct pairs $\left(j_{1}, j_{2}\right)$ give distinct powers of $r$. Hence the above determinant can be regarded as a power series with coefficients.

$$
A_{j_{1}, j_{2}}=\operatorname{det}\left[\begin{array}{l}
\sigma_{1,1} c^{i_{1}}, \sigma_{1 j_{2}}(c / 2)^{i_{1}} \\
\sigma_{2 j_{1}} c^{i_{2}}, \sigma_{2 j_{2}}(c / 2)^{i_{2}}
\end{array}\right]
$$

If $i_{1}=i_{2}$ then

$$
\operatorname{det}\left[\varphi_{i}\left(V_{j}\right)\right]_{i, j=1,2}=\left(c^{2} / 2\right)^{i_{1}} \cdot \sum_{j_{1}, j_{2}=1}^{\infty} r^{2^{2_{1}+1}+2^{2} h_{2}+2} B_{j, j_{2}}
$$

where

$$
B_{j_{1}, j_{2}}=\operatorname{det}\left[\begin{array}{l}
\sigma_{1, j_{1}}, \sigma_{1, j_{2}}  \tag{3.21}\\
\sigma_{2, j_{1}}, \sigma_{2, j_{2}}
\end{array}\right] .
$$

Since $e_{i_{1}} \otimes x_{1}, e_{i_{2}} \otimes x_{2}$ are linearly independent, not all $B_{j_{1}, j_{2}}$ are equal to 0 . Note that if $B_{j_{1}, j_{2}} \neq 0$ then $\left|B_{j_{1}, j_{2}}\right|=2$. If $i_{1} \neq i_{2}$ (we may assume $i_{1}<i_{2}$ ) then

$$
\operatorname{det}\left[\varphi_{i}\left(V_{j}\right)\right]_{i, j=1,2}=c^{i_{1}+i_{2}}\left[(1 / 2)^{i_{1}}-(1 / 2)^{i_{2}}\right] \cdot \sum_{j_{1}, h_{2}=1}^{\infty} r^{2^{2_{1}+1}+2^{2 / 2+2}} B_{j_{1}, j_{2}}
$$

where

$$
B_{j_{1}, j_{2}}=\left(1 /\left[(1 / 2)^{i^{1}}-(1 / 2)^{i_{2}}\right]\right) \cdot \operatorname{det}\left[\begin{array}{l}
\sigma_{1 j_{1}}, \sigma_{1 j_{2}}(1 / 2)^{i_{i}}  \tag{3.22}\\
\sigma_{2 j_{1}}, \sigma_{2 j_{2}}(1 / 2)^{i_{2}}
\end{array}\right] .
$$

It is clear that

$$
\begin{aligned}
1 & \leqslant\left|B_{j_{1}, j_{2}}\right| \leqslant\left[(1 / 2)^{i_{1}}+(1 / 2)^{i_{2}}\right] /\left[(1 / 2)^{i_{1}}-(1 / 2)^{i_{2}}\right] \\
& =\left[1+(1 / 2)^{i_{2}-i_{1}}\right] /\left[1-(1 / 2)^{i_{2}-i_{1}}\right] \\
& \leqslant[1+(1 / 2)] /[1-(1 / 2)]=3
\end{aligned}
$$

Applying Lemma 3.6 to the series

$$
\sum_{j_{1}, j_{2}=1}^{\infty} B_{j_{1}, j_{2}} r^{2^{2} j_{1}+1}+2^{2 z_{2}+2},
$$

where $B_{j_{1}, j_{2}}$ are defined by (3.21) or (3.22), we get $\operatorname{det}\left[\varphi_{i}\left(V_{j}\right)\right]_{i, j=1,2} \neq 0$ as required.

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